

# problem 4.1,4.2 from SHU HAO ZHE

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## 1 Chain complexes and their Homology

**1.1 Consider a commutative diagram of vectors spaces and linear maps with exact rows. Suppose that  $f_4$  is injective,  $f_1$  is surjective and  $f_2$  is injective. Show that  $f_3$  is injective. Suppose that  $f_2$  is surjective,  $f_4$  is surjective and  $f_5$  is injective. Show that  $f_3$  is surjective. In particular, we have that if  $f_1, f_2, f_4$  and  $f_5$  are isomorphisms, then  $f_3$  is an isomorphism. (This assertion is called the 5-lemma.)**

Proof. (idea: diagram chasing) We only need to prove the first statement since the other two can be solved using similar method. Set  $x \in A_3$  such that  $f_3(x) = 0$ . the only thing we need to do is to examine whether  $x = 0$  holds. Using property of commutative diagram, we obtain  $b_3(f_3(x)) = 0 = f_4(a_3(x))$ .  $f_4$  is injective, so  $a_3(x) = 0$ , or  $x \in \text{Ker} a_3 = \text{Im} a_2$ . There exists a element  $x' \in A_2$  such that  $a_2(x') = x$  and  $f_3(a_2(x')) = b_2(f_2(x')) = 0$  which means  $f_2(x') \in \text{Ker} b_2 = \text{Im} b_1$ . So there's also  $x'' \in B_1$  satisfying that  $b_1(x'') = f_2(x')$ . While  $f_1$  is surjective, we can find an element  $x''' \in A_1$  such that  $f_1(x''') = x''$  and  $b_1(f_1(x''')) = f_2(a_1(x'''))$  holds for sure. Because  $f_2$  is an injection, so we can obtain  $x' = a_1(x''')$  and finally,  $x = a_2(x') = a_2(a_1(x''')) = 0$ .

**1.2 Consider the following commutative diagram where the rows are exact sequences. Show that there exists a exact sequence**

$$0 \rightarrow \text{Ker} f_1 \rightarrow \text{Ker} f_2 \rightarrow \text{Ker} f_3 \rightarrow \text{Cok} f_1 \rightarrow \text{Cok} f_2 \rightarrow \text{Cok} f_3 \rightarrow 0.$$

Proof. Construction of the long exact sequence is actually called the Snake Lemma and proof of this profound lemma is done by three steps. First, show that  $0 \rightarrow \text{Ker} f_1 \rightarrow \text{Ker} f_2 \rightarrow \text{Ker} f_3$  is exact. Second, prove that  $\text{Cok} f_1 \rightarrow \text{Cok} f_2 \rightarrow \text{Cok} f_3 \rightarrow 0$  is also exact and this procedure is similar to the first step which is relatively easy. The last as well as hardest step is to construct a homomorphism from  $\text{Ker} f_3$  to  $\text{Cok} f_1$ . You can see precise proof from any textbook concerning about category theory.

## 2 Homotopy

**2.1 Show that "homotopy equivalence" is an equivalence relation in topological spaces.**

Proof. Just need to prove that "homotopy equivalence" is reflexive, symmetric and transitive. (1) It's trivial that homotopy equivalence relation is reflexive (We can let the continuous map  $F(x, t) = f(x)$ .) (2) If  $F(x, t)$  is a homotopy from  $f_0$  to  $f_1$ , we can simply let another continuous map  $G(x, t) = F(x, 1-t)$  which is a homotopy from  $f_1$  to  $f_0$  inversely. (3) Let  $F(x, t)$  is a homotopy from  $f_0$  to  $f_1$ , and  $G(x, t)$  is another homotopy from  $f_1$  to  $f_2$ . To prove the relation is transitive, we need to construct a homotopy from  $f_0$  to  $f_2$  which can be written as

$$H(x, t) = \begin{cases} F(x, 2t), & 0 \leq t \leq \frac{1}{2} \\ G(x, 2t - 1), & \frac{1}{2} \leq t \leq 1 \end{cases} \quad (1)$$

We can obtain that "homotopy equivalence" is an equivalence relation.

**2.2 Show that all continuous maps  $f : U \rightarrow V$  that are homotopic to a constant map induce the 0-map  $f^* : H^p(V) \rightarrow H^p(U)$  for  $p > 0$ .**

Proof. Since  $f : U \rightarrow V$  that are homotopic to a constant map which has a equivalent statement saying that the map is homotopic to identity map  $id$ . Using the same construction in the proof of the Poincaré Lemma,

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**3 Exercise by ZHĀNG BóYuǎn**

**7.3.** Show that there is no continuous map  $g : D^n \rightarrow S^{n-1}$  with  $g|_{S^{n-1}} \simeq id_{S^{n-1}}$ .

**Proof.**

Assume that  $n \geq 2$ .

For the map  $r : \mathbb{R}^n \setminus \{0\} \rightarrow \mathbb{R}^n \setminus \{0\}, r(x) = \frac{x}{\|x\|}$ , we get that  $id_{\mathbb{R}^n \setminus \{0\}}$ , because  $\mathbb{R}^n \setminus \{0\}$  always contains the line segment between  $x$  and  $r(x)$ .

If  $g$  is of the indicated type, then  $g(t \cdot r(x)), 0 \leq t \leq 1$  defines a homotopy from a constant map to  $r$ .

This shows that  $\mathbb{R}^n \setminus \{0\}$  is contractible.

Since  $H^{n-1}(\mathbb{R}^n \setminus \{0\}) \neq 0$ .

This contradicts *Poincaré Lemma*.

**8.2.** Let  $\varphi : N \rightarrow M$  be a continuous map from a smooth manifold  $N$  to a smooth submanifold  $M$  of  $\mathbb{R}^k$ . Let  $i : M \rightarrow \mathbb{R}^k$  be the inclusion. Show that  $\varphi$  is smooth if and only if  $i \circ \varphi$  is smooth.

**Proof.**

Assume that  $\varphi = (\varphi_1, \dots, \varphi_m), \varphi_s \in C^\infty(N), s = 1, \dots, m$ . i.e.  $\varphi$  is smooth.

And since  $i = (x_1, \dots, x_m, 0, \dots, 0)$ .

Then  $i \circ \varphi = (\varphi_1, \dots, \varphi_m, 0, \dots, 0)$  is smooth.

Assume that  $i \circ \varphi = (f_1, \dots, f_k), f_s \in C^\infty(M), s = 1, \dots, k$ . i.e.  $i \circ \varphi$  is smooth.

And we have map  $p : \mathbb{R}^k \rightarrow M, (x_1, \dots, x_k) \mapsto (x_1, \dots, x_m)$ ,

notice that  $f_1 = \varphi_1, \dots, f_m = \varphi_m$ ,

therefore  $\varphi = p \circ i \circ \varphi$  is smooth.

**8.6.** Let  $p_0 \in S^n$  be the "north pole"  $p_0 = (0, \dots, 0, 1)$ . Show that  $S^n \setminus \{p_0\}$  is diffeomorphic to  $\mathbb{R}^n$  under stereographic projection, i.e. the map  $S^n \setminus \{0\} \rightarrow \mathbb{R}^n$  that carries  $p \in S^n$  into the point of intersection between the line through  $p_0$  and  $p$  and the equatorial hyperplane  $\mathbb{R}^n \subseteq \mathbb{R}^{n+1}$ .

**Proof.**

$\forall p \in S^n$ , assume  $p = (x_1, \dots, x_n, x_{n+1})$ .

And assume  $q = (y_1, \dots, y_n)$  is the corresponding point of  $p$ .

Then we have  $\frac{y_1}{x_1} = \dots = \frac{y_n}{x_n} = \frac{1}{1-x_{n+1}}$ ,

therefore  $y_i = \frac{x_i}{1-x_{n+1}}, i = 1, \dots, n$ .

Because  $p \in S^n, x_1^2 + \dots + x_{n+1}^2 = 1$ ,

therefore  $y_1^2 + \dots + y_n^2 = \frac{x_1^2 + \dots + x_n^2}{(1-x_{n+1})^2} = \frac{1-x_{n+1}^2}{(1-x_{n+1})^2} = \frac{1+x_{n+1}}{1-x_{n+1}}$ ,

then compute and we know that  $x_{n+1} = \frac{\sum_{i=1}^n y_i^2 - 1}{\sum_{i=1}^n y_i^2 + 1}$ ,

therefore  $x_i = \frac{2y_i}{\sum_{i=1}^n y_i^2 + 1}$ , which means that  $S^n \setminus \{p_0\}$  is diffeomorphic to  $\mathbb{R}^n$ .

## 4 Exercise by xu yi

**2.7.** Show for  $g : V \rightarrow W$  that

$$Alt^{p+q}(f)(\omega_1 \wedge \omega_2) = Alt^p(f)(\omega_1) \wedge Alt^q(f)(\omega_2)$$

, where  $\omega_1 \in Alt^p(W), \omega_2 \in Alt^q(W)$ .

$$\begin{aligned} & \text{Proof. } Alt^{p+q}(f)(\omega_1 \wedge \omega_2)(\xi_1, \xi_2, \dots, \xi_{p+q}) \\ &= (\omega_1 \wedge \omega_2)(f(\xi_1), f(\xi_2), \dots, f(\xi_{p+q})) \\ &= \sum_{\sigma \in S(p,q)} sign(\sigma) \omega_1(f(\xi_{\sigma(1)}), f(\xi_{\sigma(2)}), \dots, f(\xi_{\sigma(p)})) \omega_2(f(\xi_{\sigma(p+1)}), f(\xi_{\sigma(p+2)}), \dots, f(\xi_{\sigma(p+q)})) \\ &= \sum_{\sigma \in S(p,q)} sign(\sigma) Alt^p(f)\omega_1(\xi_{\sigma(1)}, \dots, \xi_{\sigma(p)}) Alt^q(f)\omega_2(\xi_{\sigma(p+1)}, \dots, \xi_{\sigma(p+q)}) \\ &= (Alt^p(f)(\omega_1) \wedge Alt^q(f)(\omega_2))(\xi_1, \xi_2, \dots, \xi_{p+q}) \\ & \text{therefore } Alt^{p+q}(f)(\omega_1 \wedge \omega_2) = Alt^p(f)(\omega_1) \wedge Alt^q(f)(\omega_2). \end{aligned}$$

**2.10.** Let  $V$  be a 4-dimensional vector space and  $\epsilon_1, \dots, \epsilon_4$  a basis of  $Alt^1(V)$ . Let  $A = (a_{ij})$  be a skew-symmetric matrix and define

$$\alpha = \sum_{i < j} a_{ij} \epsilon_i \wedge \epsilon_j.$$

Show that  $\alpha \wedge \alpha = 0 \Leftrightarrow det(A) = 0$ . Say  $\alpha \wedge \alpha = \lambda \epsilon_1 \wedge \epsilon_2 \wedge \epsilon_3 \wedge \epsilon_4$ . What is the relation between  $\lambda$  and  $det(A)$ ?

$$\begin{aligned} & \text{Proof. } A = (a_{ij}) \text{ be a skew-symmetric matrix} \\ & a_{ii} = 0, a_{ij} = -a_{ji}, i \neq j \\ & \alpha \wedge \alpha = (a_{12}a_{34} - a_{13}a_{24} + a_{14}a_{23} + a_{23}a_{14} - a_{24}a_{13} + a_{34}a_{12}) \epsilon_1 \wedge \epsilon_2 \wedge \epsilon_3 \wedge \epsilon_4 \\ &= 2(a_{12}a_{34} - a_{13}a_{24} + a_{14}a_{23}) \epsilon_1 \wedge \epsilon_2 \wedge \epsilon_3 \wedge \epsilon_4 \\ & det(A) = (a_{12}a_{34} - a_{13}a_{24} + a_{14}a_{23})^2 \\ & \alpha \wedge \alpha = 0 \Leftrightarrow a_{12}a_{34} - a_{13}a_{24} + a_{14}a_{23} = 0 \Leftrightarrow det(A) = 0. \\ & \text{and if } \alpha \wedge \alpha = \lambda \epsilon_1 \wedge \epsilon_2 \wedge \epsilon_3 \wedge \epsilon_4, \text{ then } det(A) = \left(\frac{\lambda}{2}\right)^2. \end{aligned}$$

**5.3.** Can  $R^2$  be written as  $R^2 = U \cup V$  where  $U, V$  are open connected sets such that  $U \cap V$  is disconnected?

Proof.  $U, V$  are open connected sets, hence

$$H^p(U) = \begin{cases} R & p = 0 \\ 0 & p > 0 \end{cases} \quad (2)$$

$$H^p(V) = \begin{cases} R & p = 0 \\ 0 & p > 0 \end{cases} \quad (3)$$

$$H^p(R^2) = \begin{cases} R & p = 0 \\ 0 & p > 0 \end{cases} \quad (4)$$

by the Poincaré lemma.

From the Mayer-Vietoris sequence we have

$$0 \rightarrow H^0(R^2) \xrightarrow{I_*} H^0(U) \oplus H^0(V) \xrightarrow{J_*} H^0(U \cap V) \xrightarrow{\delta_*} H^1(R^2) \rightarrow \dots$$

Therefore  $H^0(U \cap V) = Im J_* = H^0(U) \oplus H^0(V) / Ker J_* = R \oplus R / Im I_* = R \oplus R / R = R, U \cap V$  is connected.